



# Do Robots Need Cognition? Does Cognition Need Robots? *(a response to Matthias Scheutz's talk)*

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## Robots in Cognition and Cognition in Robots: The Dual Role of Robots in Cognitive Science

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# Overall Response



- Matt's question:
  - “What do robots and cognition both need?”
- Matt's answer:
  - “DIARC/ADE”
- The outcome:
  - impressive demonstrations of HRI
- A more general answer (to Matt's question):
  - a sound theoretical basis
  - a computationally tractable architecture
  - a quantitative experimental methodology



# Some Superficial Reactions



- We seem to have a multiplicity of computational paradigms at our disposal, so how can we choose between them?
- The situated/embodied view of cognition doesn't always mean physical robots – so how can we know when to deploy them?
- Are we impressed with what a robot does, or simply with the fact that it does anything?
- Selecting a particular robot raises so many questions about the appropriateness of its visual, vocal and behavioural affordances - how are they characterised, and how does that impact on outcomes?
- A lot of what was discussed seemed to be uniquely relevant to HRI – what about other configurations?
- Like Matt, people often say “*language is a mess, but people are very good at it*” – maybe our view of real language is quite wrong?
- Just how much autonomy/adaptability is real? – e.g. how did the robot recognise/synthesise the word “*follow*” in the first place?



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## The Exam Question(s)

- Do robots need cognition?
- Does cognition need robots?
- Raises two core issues ...
  - what theories of cognition have been refuted by experiments with robots?
  - what robot behaviours are impossible without cognition?
- All this assumes that we know what a 'robot' is and what 'cognition' is!



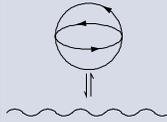
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# Cognition



- Cognition ...
  - “the mental action or process of acquiring knowledge and understanding through thought, experience, and the senses”
- Mental process ...
  - “the performance of some composite cognitive activity” !
- Q: is cognition sufficiently well defined that we can determine whether it is present or absent? (does a slug have cognition, does a tree?)
- A: if not, then we need such definitions



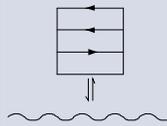
# Does Cognition Need Robots?

**“You have everything to learn from us, and we have nothing to learn from you!”**

- Q: do practitioners in the field of cognition need a physical experimental platform like a robot?
- A: probably, if their scientific questions cannot be answered by simulation
- Q: if cognition does need robots, which one(s)?
- A: robots with quantifiable capabilities in appropriate dimensions



## Do Robots Need Cognition?



- Q: is there such a thing as a robot
- A: no, so maybe some robots need cognition, and others don't
- Q: if a robot needs cognition, how much?
- A: need to define the dimensions with which cognition can be characterised, and establish capabilities and requirements
- Q: do robots needs an understanding of how living organisms behave
- A: yes, if they are to interact with them

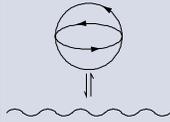


## Some Common Themes

- We seem to require a richer description of both 'cognition' and 'robot'
- We need to be able to characterise both along key dimensions that permit controlled experimentation
- We need to be able to quantify performance and requirements along such dimensions



# Cognitive Systems

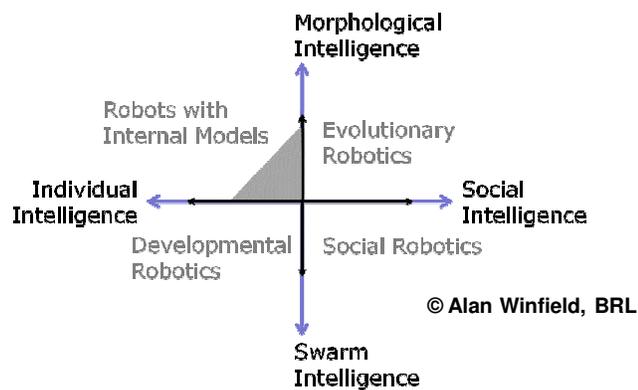
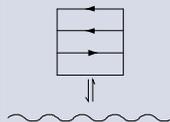


EUCog definition (*of the behaviours*) ...

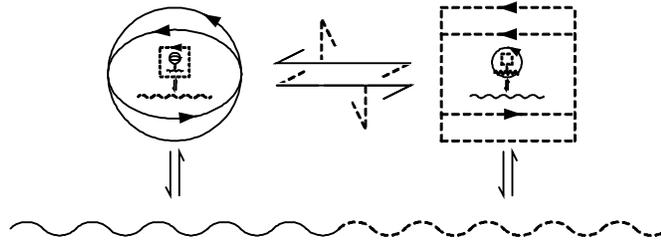
- interaction with the environment, including communication with other agents
- information processing, such as knowledge or reasoning
- adaptation, learning, flexibility
- goal directed autonomous behaviour
- (*see the wiki*)



# Robotics



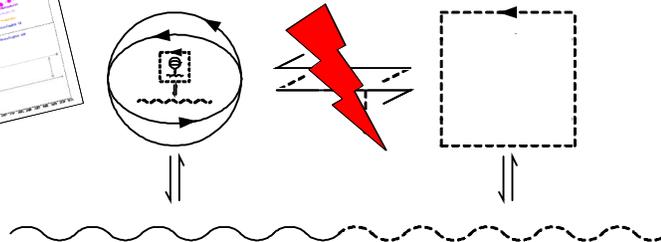
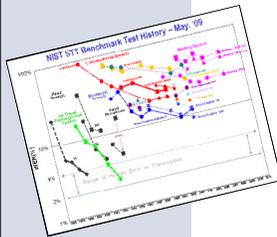
# Human-Robot Interaction



Moore, R. K. (2012). Extending Maturana and Varela's symbolic representation of autopoiesis to create a rich visual language for envisioning a wide range of enactive systems with different degrees of complexity, *Foundations of Enactive Cognitive Science*. Cumberland Lodge, Great Park of Windsor.



# Human-Robot Interaction



Moore, R. K. (2012). Keynote talk - Spoken language interaction with 'intelligent' systems: How are we doing, and what do we need to do next?, *EUCogII Workshop on Challenges for Artificial Cognitive Systems II*. Oxford.





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# Thanks for Listening

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