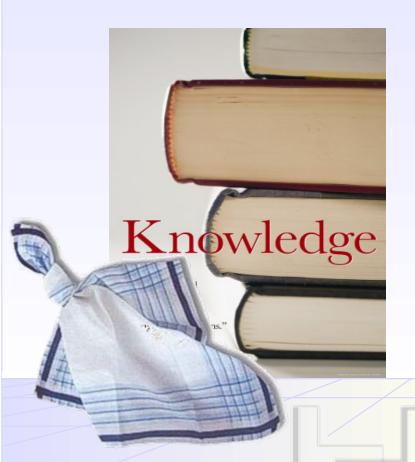
Attention modulation using short- and long-term knowledge



6th International Conference on Computer Vision Systems 2008

Sven Rebhan, Florian Röhrbein, Julian Eggert, Edgar Körner

30 August 2008

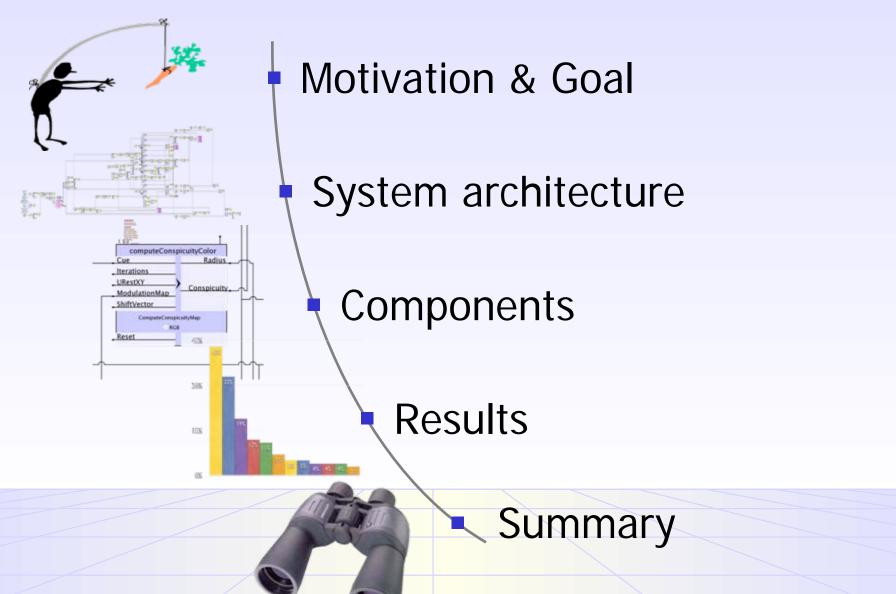
Honda Research Institute Europe GmbH D-63073 Offenbach/Main, Germany

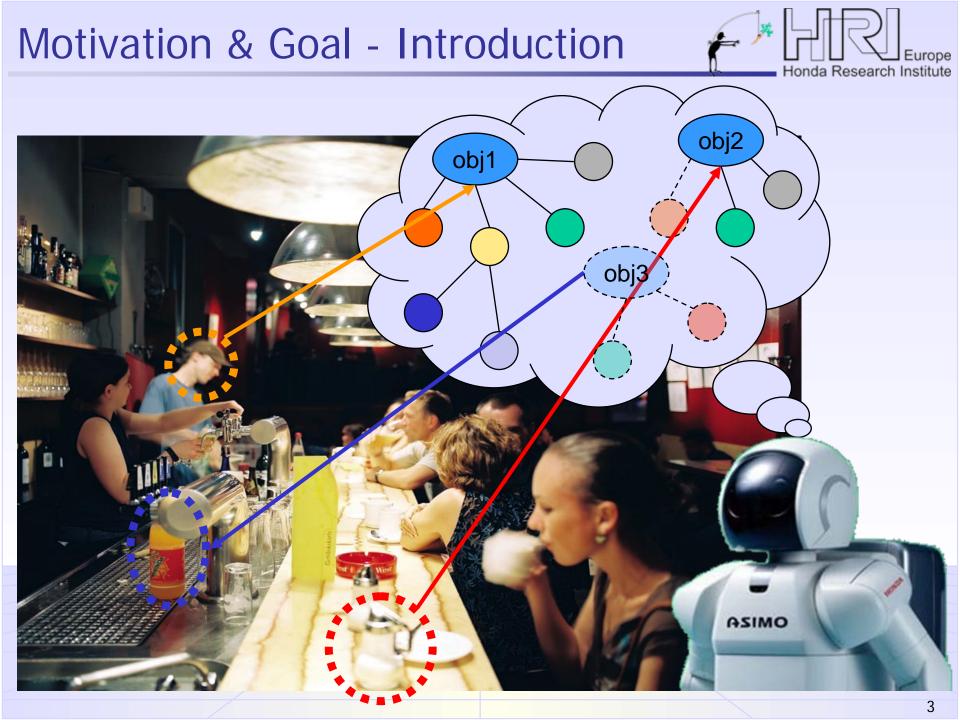
www.honda-ri.de



Outline

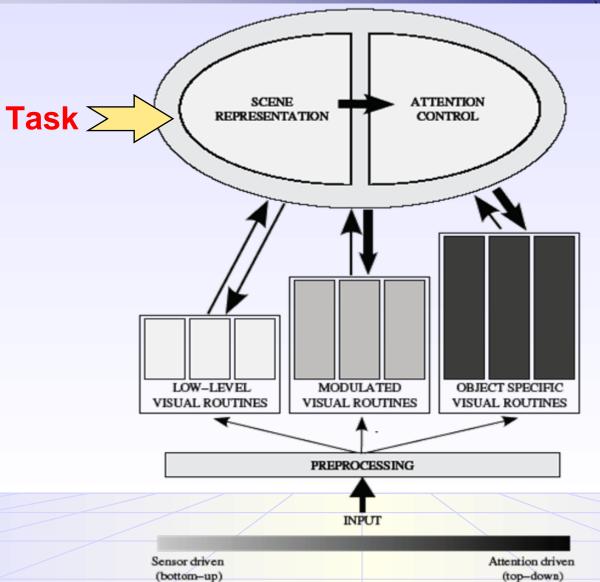






Motivation & Goal - Architecture

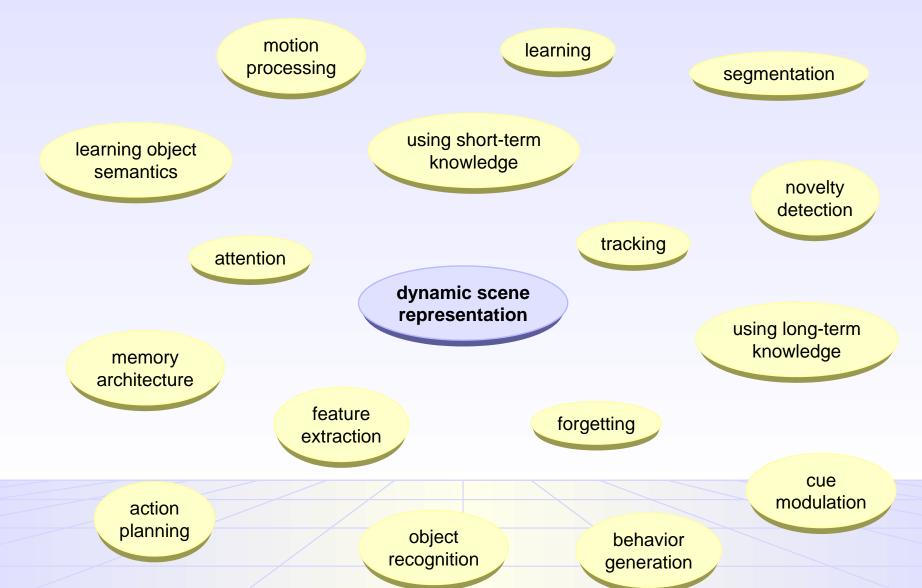




Eggert, Rebhan & Körner: First steps towards an intentional vision system, ICVS 2007

Motivation & Goal - Involved topics





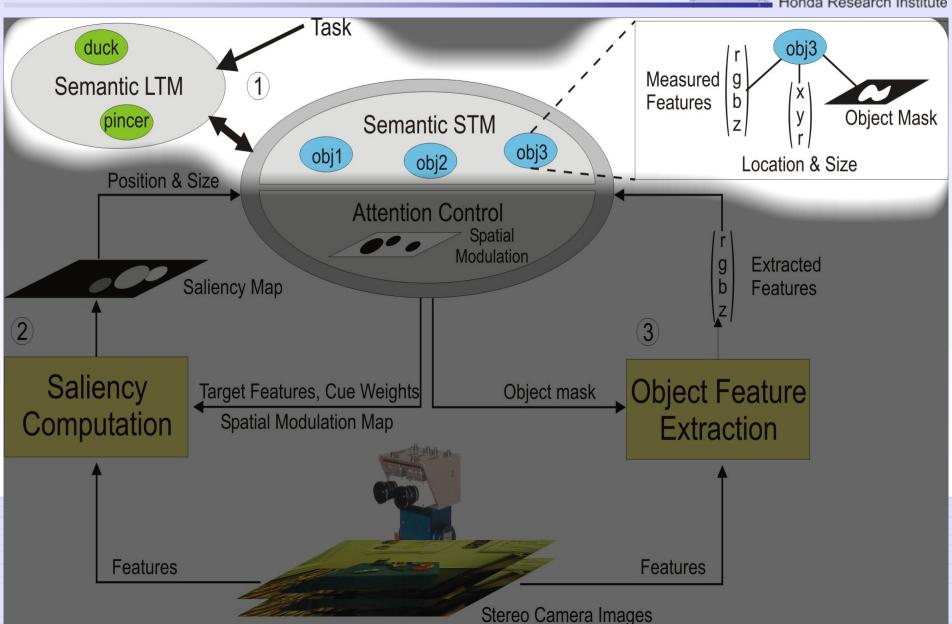
System architecture Honda Research Institute Task duck obj3 Measured 1 Semantic LTM Features Object Mask pincer Semantic STM obj3 obj1 obj2 Location & Size Position & Size Attention Control Spatial Modulation Extracted Saliency Map Features 2 3 Saliency **Object Feature** Target Features, Cue Weights Object mask Computation Spatial Modulation Map Extraction **Features** Features Stereo Camera Images

6

Components - Semantic memory



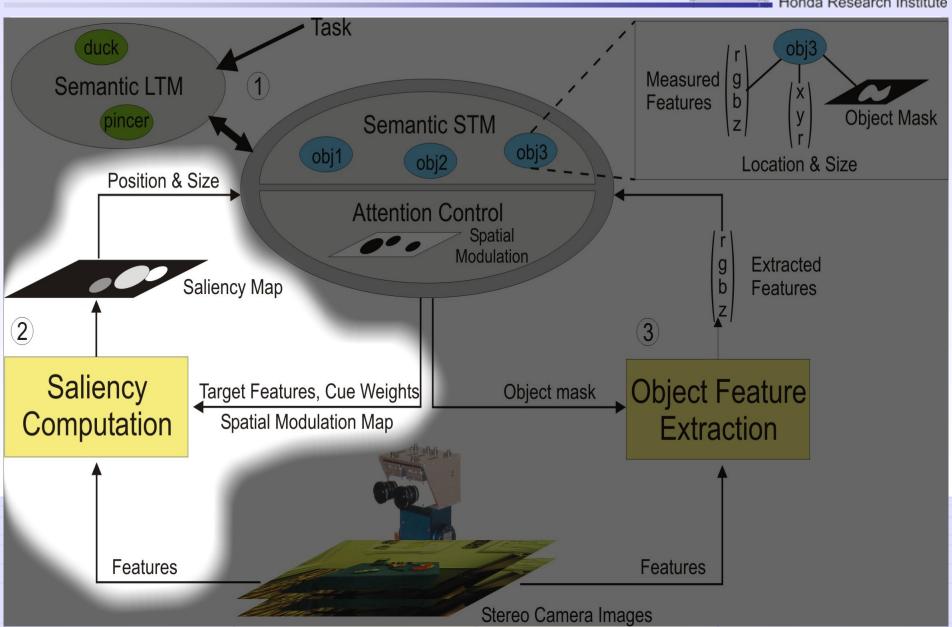




Components - Saliency



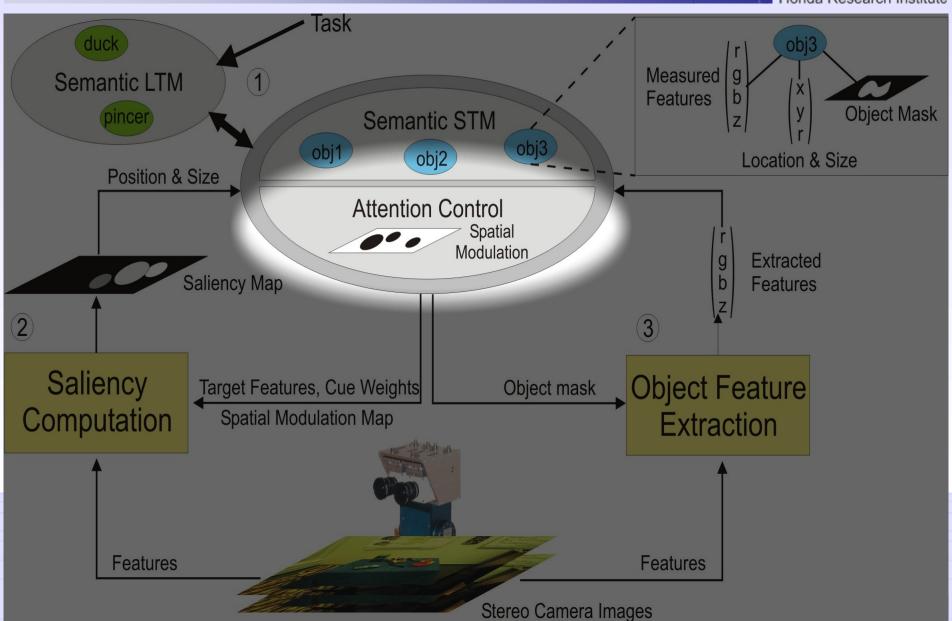




Components - Attention control

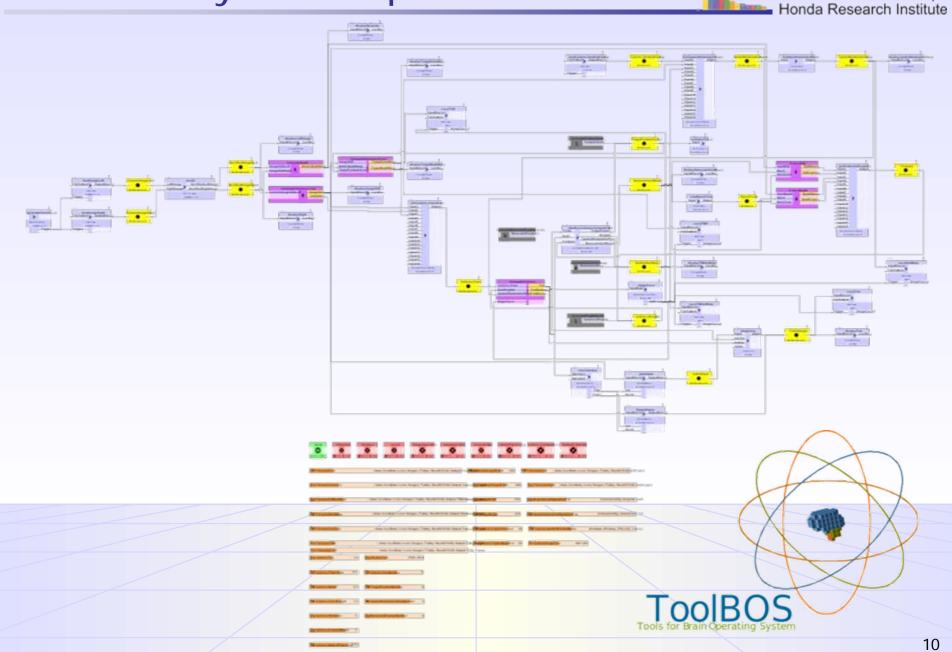






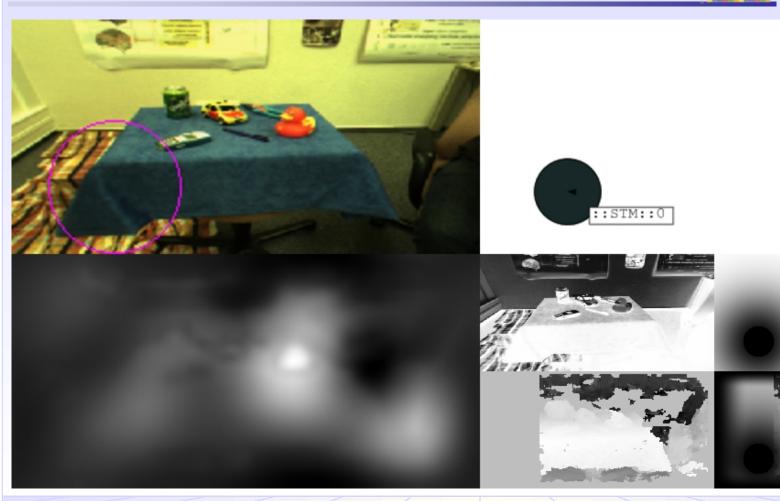
Results - System implementation





Results - Video





Summary



It's possible to:

- "fill" the scene representation in a taskspecific and sequential manner
- find familiar objects using a modulated saliency map
- speed up the visual search by using the system's short-term memory
- update visual object properties over time by using the top-down modulated saliency map



